

# Genetic Algorithms

Presented by Chen Shan-Tai

Reference:

1. Machine Learning, Chapter 9
2. Data Mining, Chapter 10
3. Tom M. Mitchell's teaching materials
4. Genetic algorithms and engineering design

# Outline

- Fundamentals of Genetic Algorithms
- GAs for TSP
- Schema Theorem
- GAs for Machine Learning
  - Classification Problems
  - Concept Learning
- Genetic Programming
- Our Story (if time permits)

# GAs

- GAs are derivative-free, stochastic-optimization methods based loosely on the concepts of natural selection and evolutionary processes.
- Properties of GAs:
  - *approximate* not *complete* methods
  - emphasizing *crossover* as the key operation
  - maintaining a population of potential solutions ([beam search](#)) while other methods process a single point of the search space.
- Problems GAs apply to:
  - No reasonably fast algorithms for the problems have been developed
  - NP-hard, hard-optimization problems, and learning tasks.

# Genetic Algorithm Vocabulary

- **Population:** initial set of random *feasible solutions*
- **Chromosome** (individual, string): a solution to the problem
- **Crossover:** operators to merge two chromosomes
- **Mutation:** operators to modify a chromosome
- **Elitism:** a strategy that ensures the propagation of the elite member, requiring that
  - the elite member selected
  - a copy of it does not become disrupted by crossover or mutation.
- A new generation formed by **Selecting** some of parents and offspring and *Rejecting* others so as to **keep the population size constant.**

# Exploitation and Exploration

- Two important issues in search strategies
- The tradeoff between *solution quality* and *convergent speed*
  - Hill-climbing: Exploiting the best solution
  - Random search: Exploring the search space
- GAs: a general-purpose search method
  - Exploration: initial population, similarity control, crossover, mutation,
  - Exploitation: fitness function, crossover, mutation

# Factors on the Convergent Speed

- Population size
- Selection scheme
- Crossover operator applying
- Mutation rate
- Forbidding of replicates
- Scaling procedures:
  - adjust objective function values to avoid rapid convergence
- ...

## Procedure: Genetic Algorithms

**begin**

$t \leftarrow 0;$  //  $t$ :  $i$ -th generations

initialize  $P(t);$  //  $P$ : parents

evaluate  $P(t);$

**while** (not termination condition) **do**

recombine  $P(t)$  to yield  $C(t);$  // crossover, mutation

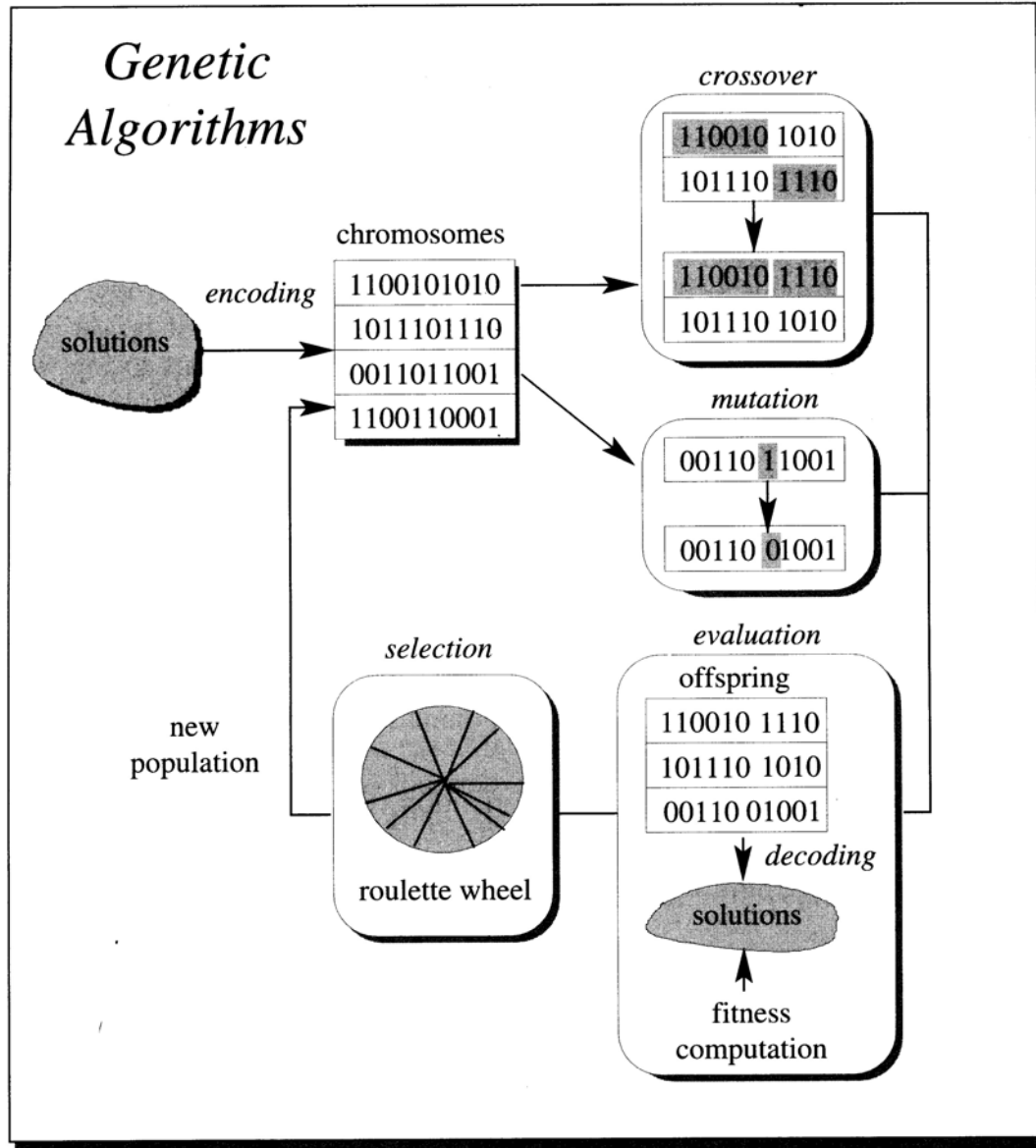
evaluate  $C(t);$  //  $C$ : children

select  $P(t + 1)$  from  $P(t)$  and  $C(t);$  // selection

$t \leftarrow t + 1;$

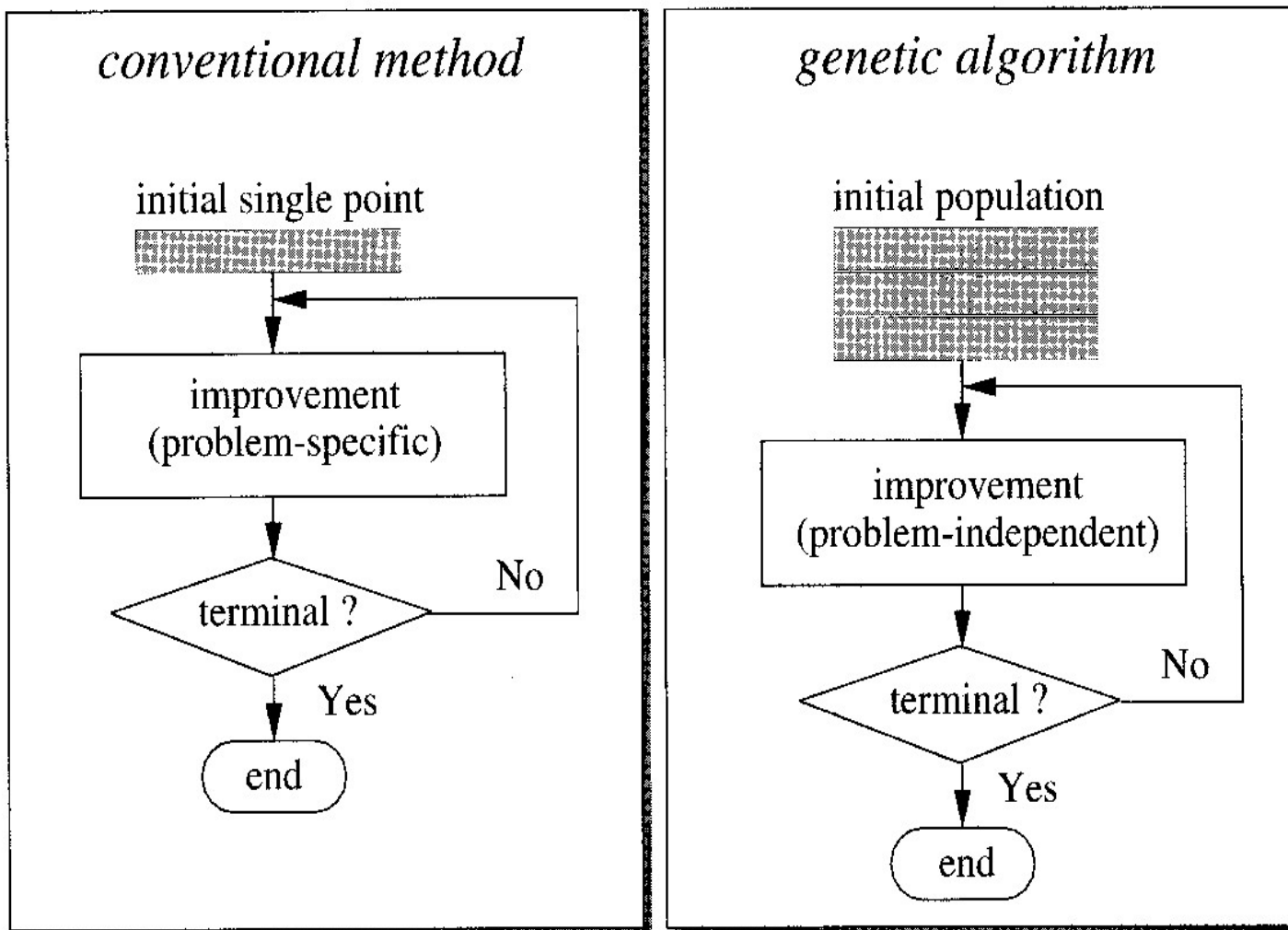
**end**

**end**



**Figure 1.1.** The general structure of genetic algorithms.





**Figure 1.2.** Comparison of conventional and genetic approaches.

# Selection

- Based on Darwinian natural selection
- High selection pressure will lead to the search terminating prematurely.
- Low selection pressure will cause the process slower than necessary
- A possible solution
  - Low selection pressure at the start of genetic search, for exploration, high selection pressure at the end, for exploitation.

# Two phases of selection

- Reproduction-selection
  - Select candidates (from parents) for mating (reproduction)
- Survival-selection
  - Select candidates to form the next generation
  - Normally, selection refers this phase

# Selection Methods

- Proportional (roulette) selection:

- Probability of selection is proportional to the individual's **fitness**.

Fitness proportionate selection:

$$\Pr(h_i) = \frac{Fitness(h_i)}{\sum_{j=1}^p Fitness(h_j)}$$

- Ranking method:

- All Individuals are sorted, and probabilities of their selection are according to their **ranking rather than their fitness**.

- Tournament selection:

- Some number, e.g., 2, of individuals compete for selection
- The competition step is repeated *popsiz*e times for each generation.
- More diverse

# Issues for Selection phase

- Sampling space:
  - Regular sampling space and [Enlarged Sampling space](#)
- Sampling mechanism: how to select chromosomes from sampling space
  - *Stochastic sampling*: based on its survival probability,
    - Ex: roulette wheel selection
  - Deterministic sampling: select the best k individuals
  - Mixed sampling
- Selection probability
  - Scaling (or ranking) mechanisms: to maintain a reasonable differential so as to prevent a too-rapid premature
  - Static scaling and Dynamic scaling, to adjust the selective pressure.

# Enlarged sampling space

- Both parents and children have the same chance of competing for survival
- $(\mu+\lambda)$  selection:
  - $\mu$  *parents* and  $\lambda$  *offspring* compete for survival and the  $\mu$  **best** out of offspring and old parents are selected as parents of the next generation.
- **Vs.**  $(\mu, \lambda)$  selection: **regular sampling**
  - Select  $\mu$  best **offspring** as parents of the next generation, where  $\mu < \lambda$ .

# The word-matching problem: “tobeornottobe”

The representation: a~z → 97~122

[116, 111, 98, 101, 111, 114, 110, 111, 116, 116, 111, 98, 101]

Generate an initial population of 10 random phrases as follows:

[114, 122, 102, 113, 100, 104, 117, 106, 97, 114, 100, 98, 101]

[110, 105, 101, 100, 119, 118, 121, 118, 106, 97, 104, 102, 106]

[115, 99, 121, 117, 101, 105, 115, 111, 115, 113, 118, 99, 98]

[102, 98, 102, 118, 114, 97, 109, 116, 101, 107, 117, 118, 115]

[107, 98, 117, 113, 114, 116, 106, 116, 106, 101, 110, 115, 98]

[102, 119, 121, 113, 121, 107, 107, 116, 122, 121, 111, 106, 104]

[116, 98, 120, 98, 108, 115, 111, 105, 122, 103, 103, 119, 109]

[101, 111, 111, 117, 114, 104, 100, 120, 98, 118, 116, 120, 97]

[100, 116, 114, 105, 117, 111, 115, 114, 103, 107, 109, 98, 103]

[106, 118, 112, 98, 103, 101, 109, 116, 112, 106, 97, 108, 113]

Now, we convert this population to string to see what they look like:

rzfqdhujardbe  
niedwvyvjahfj  
scyueisosqvcb  
fbfvramtekUvs  
kbuqrtjtjensb  
fwyqykktzyojh  
tbxblsoizggwm  
dtriuosrgkmbg  
jvpbgemtpjalq

- Fitness function: # of matched letters
- Selection: the top 50% better individuals
- Search space:  $26^{13}$
- # of generations to match: 23

# The best String for Each Generation

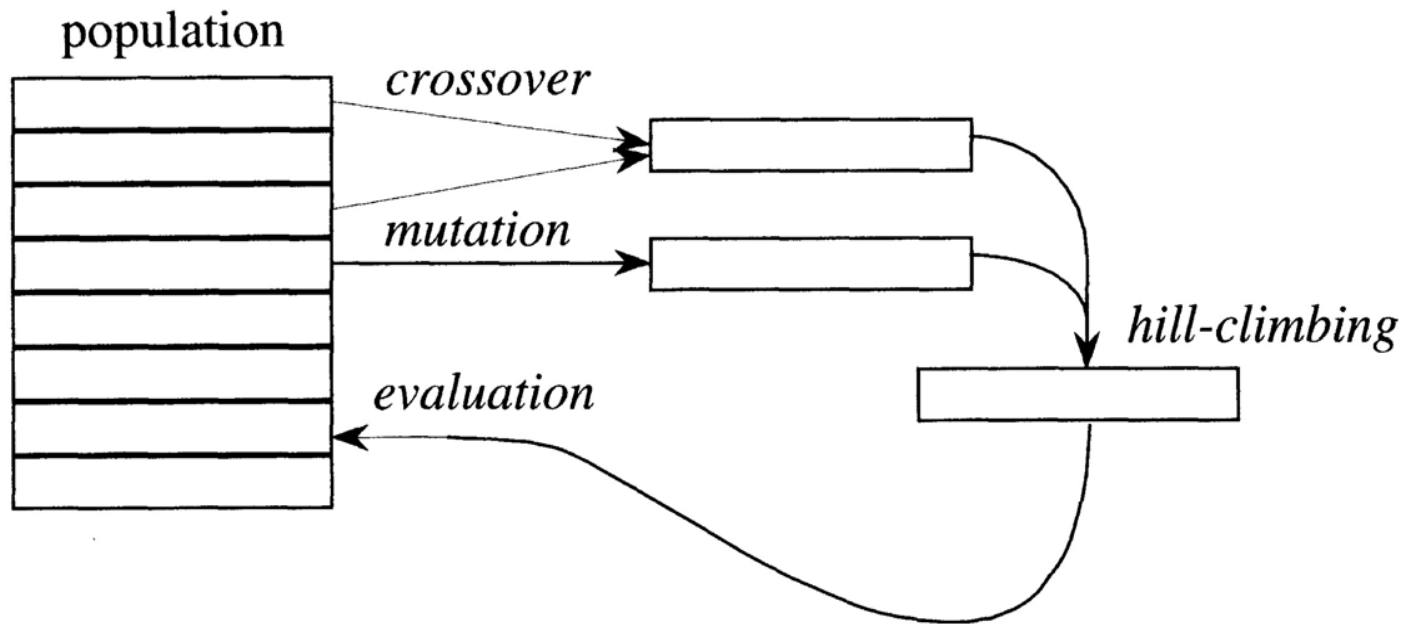
Generation	String	Fitness	Generation	String	Fitness
1	rzfqdhujardbe	2	16	rbzwornottobe	10
2	rzfqdhuoardbe	3	17	rbzwornottobe	10
3	rzfqghuoatdbe	4	18	rbzwornottobe	10
4	rzfqghuoztobe	5	19	rbzwornottobe	10
5	rzfqghhottobe	6	20	robzwornottobe	11
6	rzfqohhottobe	7	21	tobzwornottobe	12
7	rzfqohnottobe	8	22	tobzwornottobe	12
8	rzfqohnottobe	8	23	tobeornottobe	13
9	rzfqohnottobe	8	24	tobeornottobe	13
10	rzfqohnottobe	8	25	tobeornottobe	13
11	rzfqornottobe	9	26	tobeornottobe	13
12	rzfqornottobe	9	27	tobeornottobe	13
13	rwwornottobe	9	28	tobeornottobe	13
14	rwcwornottobe	9	29	tobeornottobe	13
15	rzcwornottobe	9	30	tobeornottobe	13



# Hybrid GAs

- *Genetic algorithms* are used to perform global exploration among population, while *heuristic methods*, e.g. hill\_climbing, are used to perform local exploitation around chromosomes.
- Try to inject some “smarts” into the offspring before returning it to be evaluated.

*hybrid GA based on Darwin 's & Lamarck's evolution*



**Figure 1.10.** General structure of hybrid genetic algorithms.

# GAs for TSP

# A GA for TSP

- Representations:
  - *permutations* instead of binary strings
- Crossover:
  - OX, CX, PMX, ...
- Mutation:
  - hill-climbing
- Selection:
  - The lower cost individuals

**Algorithm 5.26:** GENETICTSP ( $popsize, c_{max}$ )

**external** SELECT(), REC()

$c \leftarrow 1$


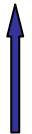
$[P_0, \dots, P_{popsize-1}] \leftarrow \text{SELECT}(popsize)$

Sort  $P_0, P_1, \dots, P_{popsize}$  in increasing order of cost

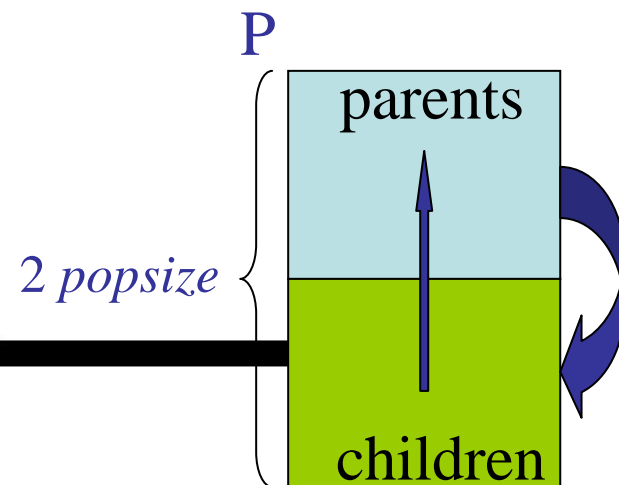
$X_{best} \leftarrow P_0$

$BestCost \leftarrow C(P_0)$

**while**  $c \leq c_{max}$

**do** {  
  **for**  $i \leftarrow 0$  **to**  $popsize/2 - 1$   // crossover, mutation  
  **do**  $(P_{popsize+2i}, P_{popsize+2i+1}) \leftarrow \text{Rec}(P_{2i}, P_{2i+1})$   
  Sort  $P_0, P_1, \dots, P_{2 \cdot popsize - 1}$  in increasing order of cost  //sort  
   $CurCost \leftarrow C(P_0)$   
  **if**  $CurCost < BestCost$   
  **then** {  
     $X_{best} \leftarrow P_0$   
     $BestCost \leftarrow CurCost$   
  }  
   $c \leftarrow c + 1$

**return** ( $X_{best}$ )



# Variant Representations and Recombination solutions for TSP

- The binary string representations  $\rightarrow$  permutations
- The typical one-point crossover may lead to infeasible solutions, e.g., not permutations
- A Solution: -- the PMRec algorithm
  - Choose two crossover points, 2, 5, randomly
  - Parents: A=[3,1,4,7,6,5,2,8], B=[8,6,4,3,7,1,2,5]
  - Transpositions of symbols:
    - $4 \leftrightarrow 4$ , A=[3,1,4,7,6,5,2,8], B=[8,6,4,3,7,1,2,5]
    - $7 \leftrightarrow 3$ , A=[7,1,4,3,6,5,2,8], B=[8,6,4,7,3,1,2,5]
    - $6 \leftrightarrow 7$ , A=[6,1,4,3,7,5,2,8], B=[8,7,4,6,3,1,2,5]
    - $5 \leftrightarrow 1$ , **C=[6,5,4,3,7,1,2,8], D=[8,7,4,6,3,5,2,1]**
- Other better solutions?

**Algorithm 5.25: MGKREC ( $A, B$ )**

**external** RandomInteger(), STEEPESTASCENTTWOOPT()

$h \leftarrow \text{RandomInteger}(10, \frac{n}{2})$

$j \leftarrow \text{RandomInteger}(0, n - 1)$

$T \leftarrow \emptyset$

**for**  $i \leftarrow 0$  **to**  $h - 1$  **do**  $\begin{cases} D[i] \leftarrow B[(i + j) \bmod n] \\ T \leftarrow T \cup \{D[i]\} \end{cases}$

**for**  $j \leftarrow 0$  **to**  $n - 1$

**do if**  $A[j] \notin T$

**then**  $\begin{cases} D[i] \leftarrow A[j] \\ i \leftarrow i + 1 \end{cases}$

STEEPESTASCENTTWOOPT( $D$ )

$j \leftarrow \text{Random}(0, n - 1)$

$T \leftarrow \emptyset$

**for**  $i \leftarrow 0$  **to**  $h - 1$  **do**  $\begin{cases} C[i] \leftarrow A[(i + j) \bmod n] \\ T \leftarrow T \cup \{C[i]\} \end{cases}$

**for**  $j \leftarrow 0$  **to**  $n - 1$

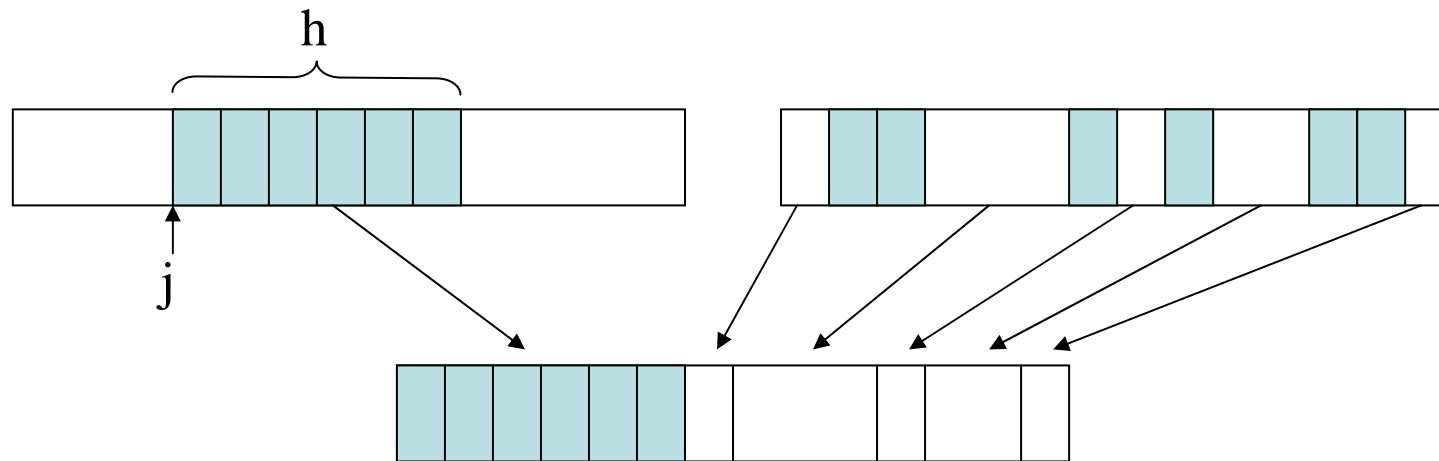
**do if**  $B[j] \notin T$

**then**  $\begin{cases} C[i] \leftarrow B[j] \\ i \leftarrow i + 1 \end{cases}$

STEEPESTASCENTTWOOPT( $C$ )

**return** ( $C, D$ )

# A Better Crossover for TSP-- MGKRec



- Generate  $j, h$  randomly, where  $0 \leq j \leq n-1, 4 \leq h \leq n/2$
- EX:  $(j, h) = (5, 4)$ 
  - $A = [3, 1, 4, 7, 6, 5, 2, 8], B = [8, 6, 4, 3, 7, 1, 2, 5]$
  - $C = [5, 2, 8, 3, 6, 4, 7, 1]$
- In a similar way,  $D = [2, 5, 8, 6, 3, 1, 4, 7]$  for  $(j, h) = (6, 4)$
- Two strategies: remains the green part in the middle part or two ends.



# Schema Theorem

# Schema Theorem (1975,1989)

- *Schemata that are short, low-order, and above-average are given exponentially increasing numbers of trials in subsequent generations of a genetic algorithm.*
- theoretical foundations of genetic algorithms
- Introduced by *Holland* and popularized by *Goldberg*

# Schema(ta)

- A schema describes a subset of strings with similarities at some string positions; i.e., it defines a subset of the search space.
- A template allowing exploration of **similarities** among chromosomes

# Number of Schemata

- A given binary *real string* of length  $L$ :  $2^L$ 
  - E.g.,  $2^3$  schemata for the string 101
- An alphabet of distinct characters  $k$ :  $(k+1)^L$ 
  - E.g.,  $3^2$  schemata for binary strings ( $k=2$ ) of length 2
  - 00, 01, 0#, 10, 11, 1#, #0, #1, ##
- A population of  $N$  real strings:  $Nk^L$ 
  - Actually, it will be always  $< Nk^L$  because of sharing

# Properties of Schemata

E.g.,  $H_a = 1###$ ,  $H_b = 1##0$ ,  $H_c = \#001$

- **Order(O)**: number of non-#,
  - reflecting how large the covering regions of space
  - the probability of a schema destroyed by a *mutation*
  - $O(H_a)=1$ ,  $O(H_b)=2$ ,  $O(H_c)=3$
- **Length(L)**:
  - the difference between the first and the last non-# symbols,
  - the probability of a schema destroyed by a *crossover*
  - $O(H_a)=0$ ,  $O(H_b)=3$ ,  $O(H_c)=2$
- **Fitness(F)**: the average fitness of all strings in the population matched by a schema, S, at time t

$$F(S, t) = \left[ \sum_{i=1}^p f(v_i) \right] / p$$

$\{v_1, v_2, \dots, v_p\}$ : p strings in a population matched by S

# Schema Growth Equation (consider just selection)

- $\bar{f}(t)$  = average fitness of pop. at time  $t$
- $m(s, t)$  = instances of schema  $s$  in pop at time  $t$
- $\hat{u}(s, t)$  = ave. fitness of instances of  $s$  at time  $t$

Probability of selecting  $h$  in one selection step

$$\begin{aligned}\Pr(h) &= \frac{f(h)}{\sum_{i=1}^n f(h_i)} \\ &= \frac{f(h)}{n\bar{f}(t)}\end{aligned}$$

Probability of selecting an instance of  $s$  in one step

$$\begin{aligned}\Pr(h \in s) &= \sum_{h \in s \cap p_t} \frac{f(h)}{n\bar{f}(t)} \\ &= \frac{\hat{u}(s, t)}{n\bar{f}(t)} m(s, t)\end{aligned}$$

Expected number of instances of  $s$  after  $n$  selections

$$E[m(s, t + 1)] = \frac{\hat{u}(s, t)}{\bar{f}(t)} m(s, t)$$

# Schema Theorem

$$E[m(s, t+1)] \geq \overset{\text{selection}}{\frac{\hat{u}(s, t)}{\bar{f}(t)} m(s, t)} \overset{\text{crossover}}{\left(1 - p_c \frac{d(s)}{l-1}\right)} \overset{\text{mutation}}{(1-p_m)^{o(s)}}$$

- $m(s, t)$  = instances of schema  $s$  in pop at time  $t$
- $\bar{f}(t)$  = average fitness of pop. at time  $t$
- $\hat{u}(s, t)$  = ave. fitness of instances of  $s$  at time  $t$
- $p_c$  = probability of single point crossover operator
- $p_m$  = probability of mutation operator
- $l$  = length of single bit strings
- $o(s)$  number of defined (non “\*”) bits in  $s$
- $d(s)$  = distance between leftmost, rightmost defined bits in  $s$

# GAs for Machine Learning

## *Part I: Classification*



# Machine Learning Using GAs

- To discover input-output mapping for a given, usually complex, *system* (a set of input-output samples)
  - To come up with an appropriate form of **a function** or **a model**, simpler than the given system
- Expect that the population of *classifiers* converges to some **rules** with very high **strength**.
- Successful applications:
  - Pattern classification, control, and prediction

# Classification Model

- The description of the model (a conjunction normal form)

$$((A_1=x) \wedge (A_5=s)) \vee ((A_1=y) \wedge (A_4=n)) \Rightarrow C_1$$

$$((A_3=y) \wedge (A_4=n)) \vee (A_1=x) \Rightarrow C_2$$

- The training or learning data set is described with a set of attributes where each attribute has its categorical *range* (a set of possible values)
- Table 10.4

# Classification rules (classifiers)

- The general form of each classifier

$$(p_1, p_2, \dots, p_{\# \text{ of attributes}}): d$$

- Generate classifiers from models

$$- ((A_1=x) \wedge (A_5=s)) \vee ((A_1=y) \wedge (A_4=n)) \Rightarrow C_1$$

- $(x^{***}s^*): C_1$

- $(y^{**}n^{**}): C_1$

$$- ((A_3=y) \wedge (A_4=n)) \vee (A_1=x) \Rightarrow C_2$$

- $(^{**}yn^{**}): C_2$

- $(x^{*****}): C_2$

# Fitness of classifiers: Strength

- Strengths  $S_i$  are proportional to the percentage of the data set supported by the classifier (rule).
- GAs try to optimize *the set of rules* with respect to the fitness function of the rules to training data set.

# Mutation

- Randomly choose a position  $i$ , e.g., 2,
  - Randomly choose a value from the domain of  $p_i$ , e.g., \*
  - The strength of the offspring is usually the same as that of its parents.
- 
- E.g.,  $(xy^{****}):1, s=8.7$   
     $\rightarrow (x_{-}^{*****}):1, s=8.7$

# Crossover

- Select two parents.
- Generate a random crossover-position point, e.g., 3.
- The strength of the offspring is an average of the parents' strengths.
- E.g.,
  - Parents:     (\*\*\*) ms\*):1; (\*\*y \*\*n):0
  - Offspring:   (\*\*\*) \*\*n):0; (\*\*y ms\*):1

# GAs for Machine Learning

## *Part II: Concept Learning*

# Fitness Functions

- To learn classification rule
  - The classification accuracy of the individual (rule, hypothesis) over a set of provided training examples
- To learn a program for solving *block problems*
  - The number of training examples the individual can solve (*Genetic Programming*)
- To learn a strategy for playing a game
  - The number of games won by the individual (strategy) when playing against other individuals in the current population. (*Genetic Programming*)



# Representing Hypotheses— *Bit String Representation*

Represent

$(Outlook = Overcast \vee Rain) \wedge (Wind = Strong)$

by

*Outlook* *Wind*  
011      10

*Outlook* = {sunny, overcast, rain}

*Wind* = {strong, weak}

*PlayTennis* = {yes, no}

Represent

IF *Wind* = *Strong* THEN *PlayTennis* = *yes*

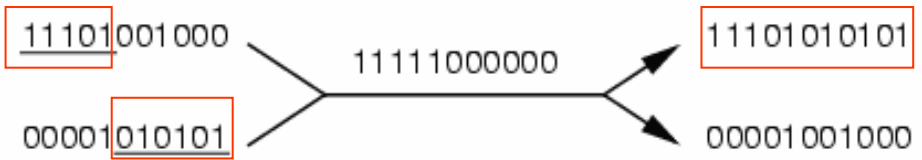
by

*Outlook* *Wind* *PlayTennis*  
111      10      10

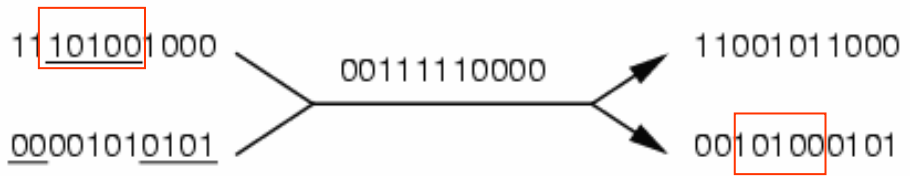
# Operators for GAs

*Initial strings*      *Crossover Mask*      *Offspring*

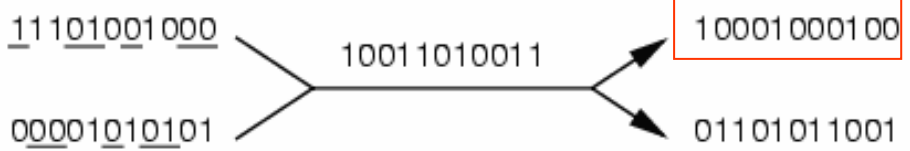
*Single-point crossover:*



*Two-point crossover:*



*Uniform crossover:*



*Point mutation:*



# Example for Concept Learning

## *GABIL (1993)*

**Fitness:**

$$Fitness(h) = (\text{correct}(h))^2$$

the percent of all training examples  
correctly classified by  $h$

**Representation:**

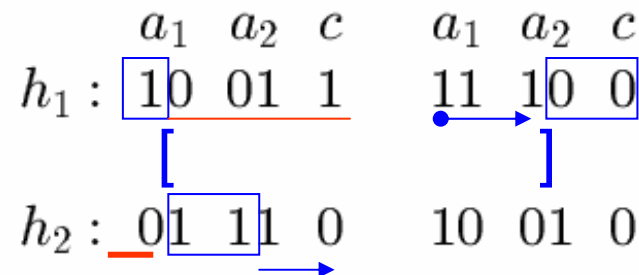
IF  $a_1 = T \wedge a_2 = F$  THEN  $c = T$ ; IF  $a_2 = T$  THEN  $c = F$

represented by

$a_1$	$a_2$	$c$	$a_1$	$a_2$	$c$
10	01	1	11	10	0

# Crossover with variable-length bit string

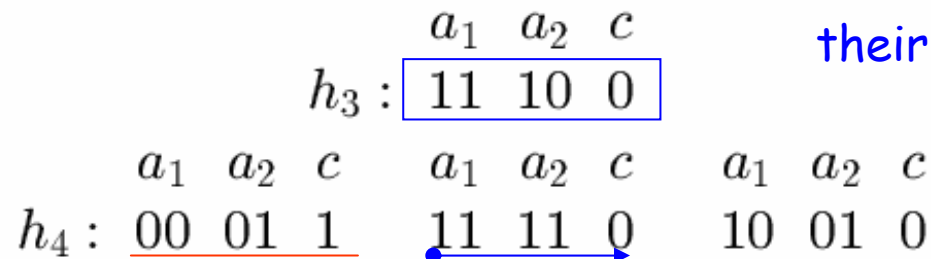
Start with



1. choose crossover points for  $h_1$ , e.g., after bits 1, 8
2. now restrict points in  $h_2$  to those that produce bitstrings with well-defined semantics, e.g.,  $\langle 1, 3 \rangle$ ,  $\langle 1, 8 \rangle$ ,  $\langle 6, 8 \rangle$ .

if we choose  $\langle 1, 3 \rangle$ , result is

Enable offspring to contain a different number of rules than their parents



# GABIL Extensions

- Add two GA operators
  - AddAlternative (AA):
    - Generalize constraint on  $a_i$  by changing a 0 to 1 in a substring.
  - DropCondition (DC):
    - Completely dropping the constraint on  $a_i$  by replacing all bits for  $a_i$  by a 1.
- Furthermore, add two bits to determine which of the operators can be applied to the hypotheses.

$a_1$	$a_2$	$c$	$a_1$	$a_2$	$c$	AA	DC
01	11	0	10	01	0	1	0

# GABIL Results

Performance of GABIL comparable to symbolic rule/tree learning methods C4.5, ID5R, AQ14

Average performance on a set of 12 synthetic problems:

- GABIL without *AA* and *DC* operators: 92.1% accuracy
- GABIL with *AA* and *DC* operators: 95.2% accuracy
- symbolic learning methods ranged from 91.2 to 96.6

# Genetic Programming

# Genetic Programming (GP)

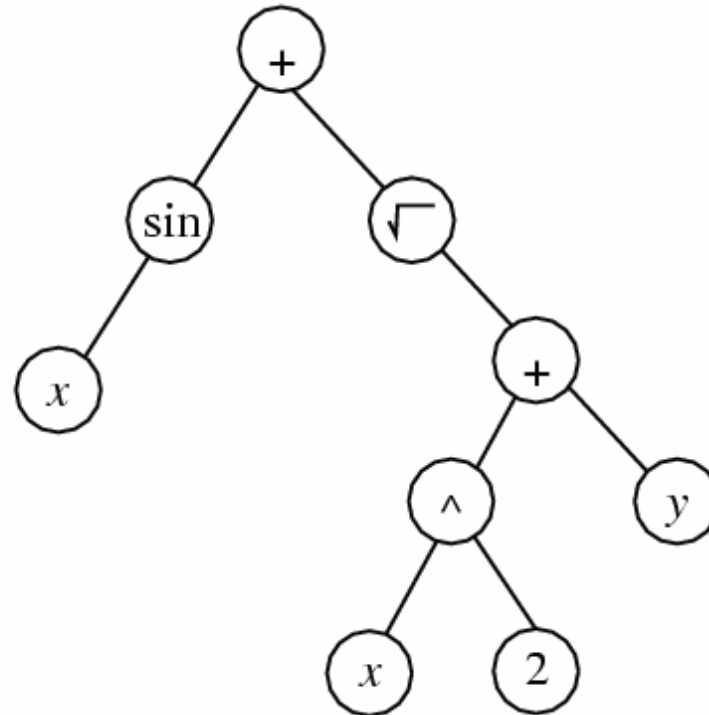
- The individuals are *computer programs* rather than bit strings.
- The programs are typically represented by trees corresponding to the parse tree of the program.
- The fitness of a individual program is determined by executing the program on a set of training data.
- Program tree representation. [#36](#)



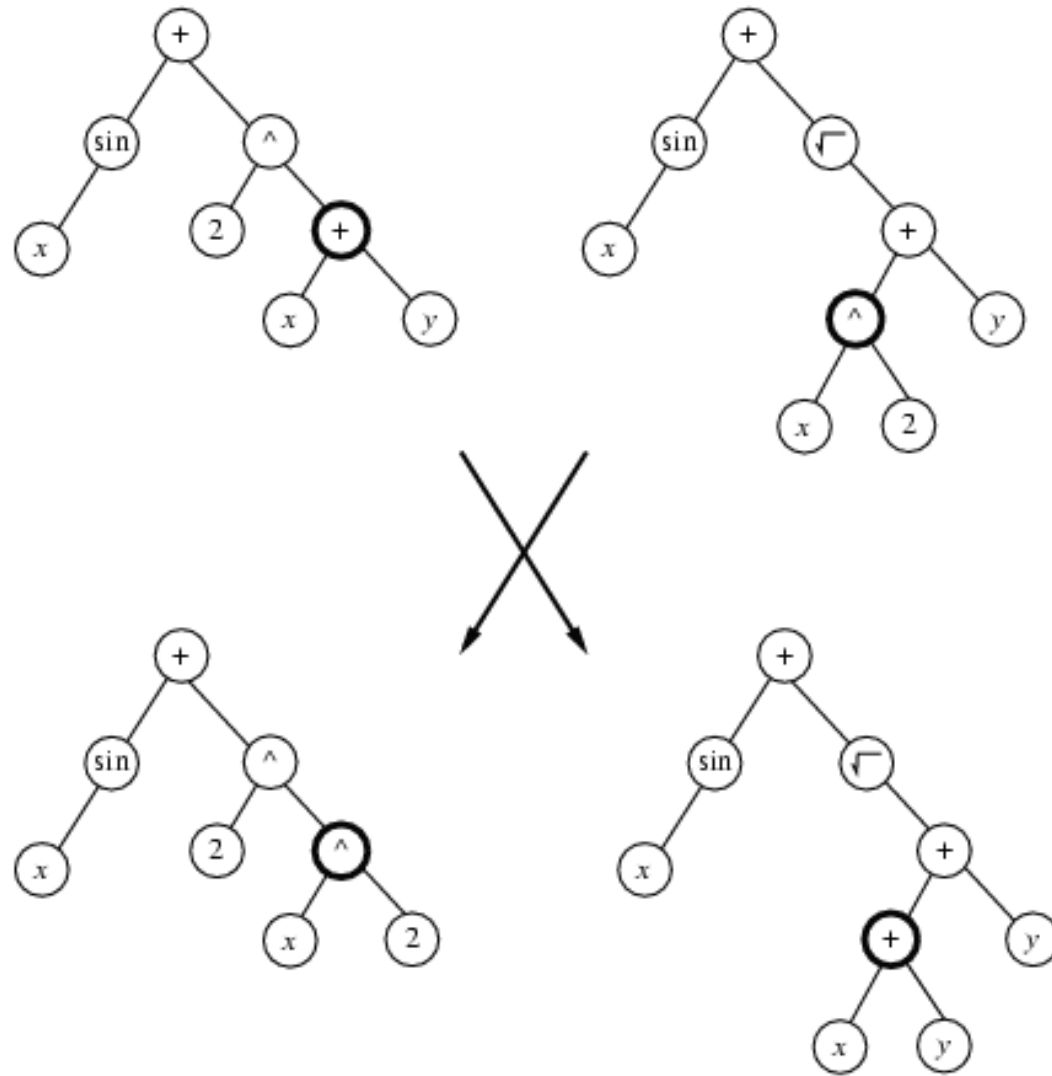
# Program tree representation

Population of programs represented by trees

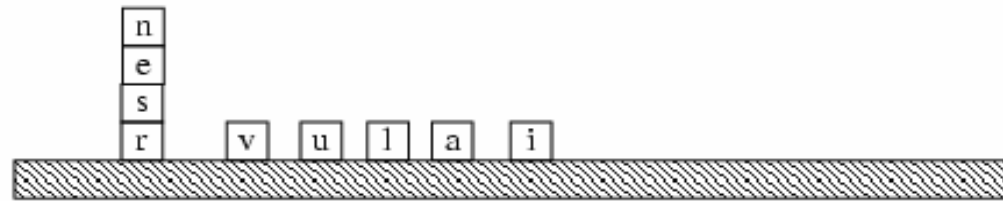
$$\sin(x) + \sqrt{x^2 + y}$$



# Crossover Operation



# Block Problems



Goal: spell UNIVERSAL

Terminals:

- CS (“current stack”) = name of the top block on stack, or  $F$ .
- TB (“top correct block”) = name of topmost correct block on stack
- NN (“next necessary”) = name of the next block needed above TB in the stack

# Primitive functions

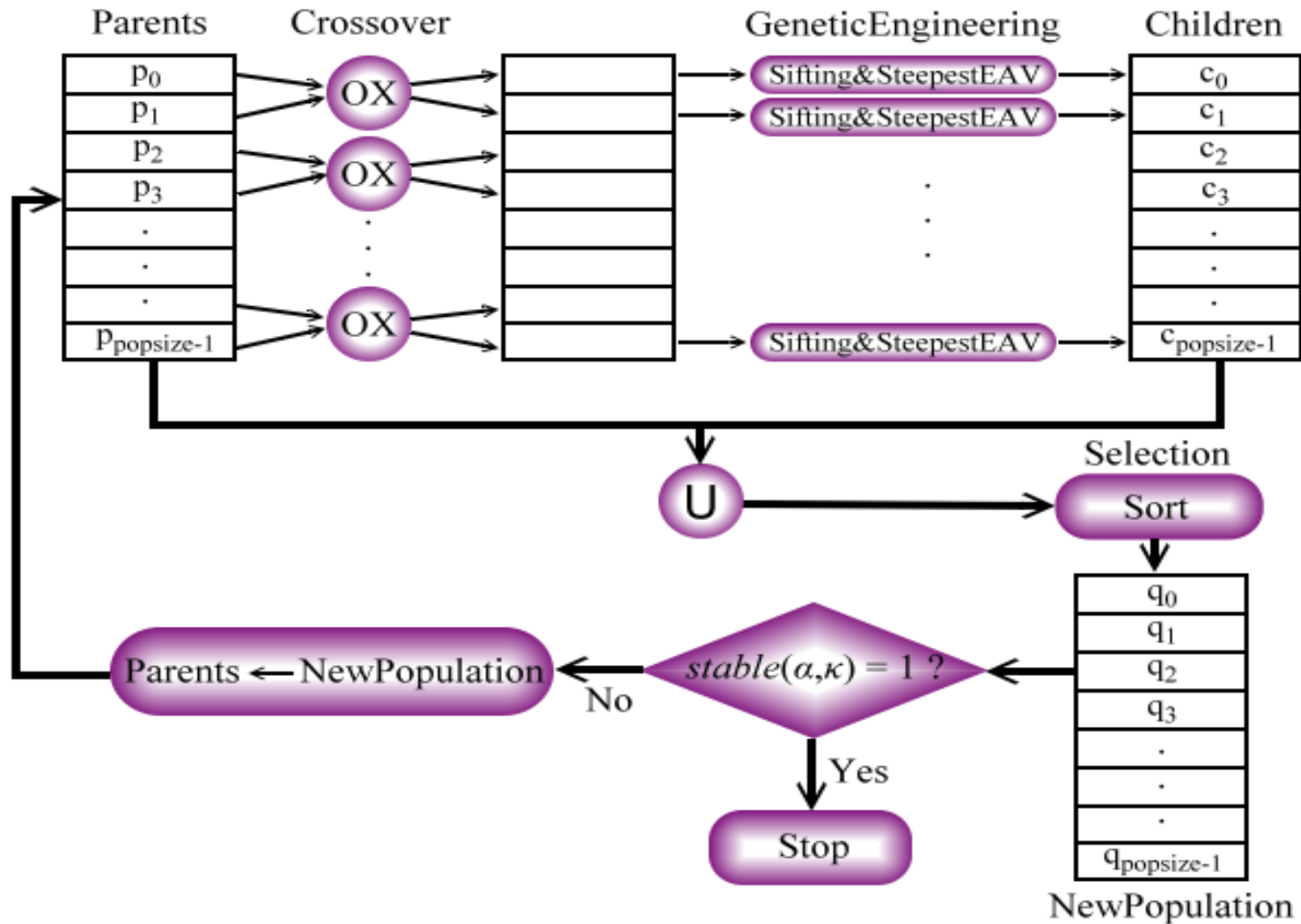
- (MS  $x$ ): (“move to stack”), if block  $x$  is on the table, moves  $x$  to the top of the stack and returns the value  $T$ . Otherwise, does nothing and returns the value  $F$ .
- (MT  $x$ ): (“move to table”), if block  $x$  is somewhere in the stack, moves the block at the top of the stack to the table and returns the value  $T$ . Otherwise, returns  $F$ .
- (EQ  $x y$ ): (“equal”), returns  $T$  if  $x$  equals  $y$ , and returns  $F$  otherwise.
- (NOT  $x$ ): returns  $T$  if  $x = F$ , else returns  $F$
- (DU  $x y$ ): (“do until”) executes the expression  $x$  repeatedly until expression  $y$  returns the value  $T$

# Learned Program

- Goal: train an individual (program) to fit 166 training examples (block problems)
- Fitness: The number of training examples the individual can solve
- Initialize 300 random programs
- After 10 generations, the system discovered the following program, which can solve all 166 problems.

```
(EQ (DU (MT CS)(NOT CS)) (DU (MS NN)(NOT NN)) )
```

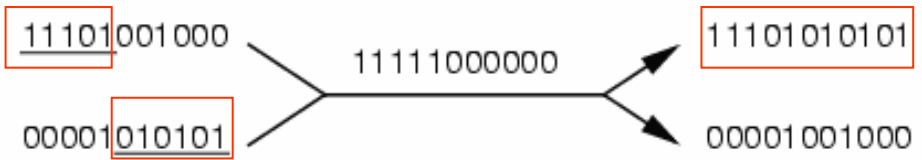
# EBEA



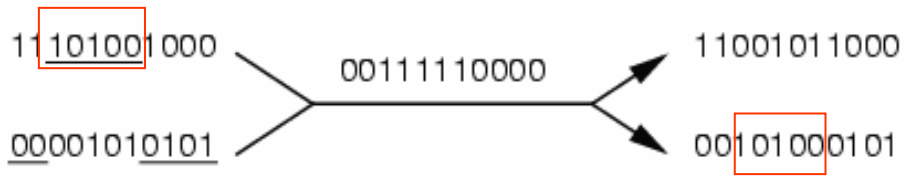
# Operators for GAs

*Initial strings*      *Crossover Mask*      *Offspring*

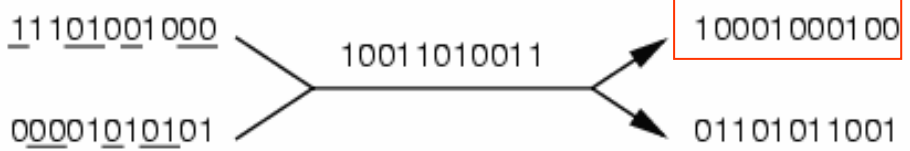
*Single-point crossover:*



*Two-point crossover:*



*Uniform crossover:*



*Point mutation:*

